

from 310V to 225V at 400ms when the gain of the ES is 0.05. As shown in Fig. 16(a), the current is significantly reduced from 10A to 6A, which implies that the active power is reduced from 1550W to 675W. When the gain of the ES is 0.2, as shown in Fig. 16(b), V_l drops from 310V to 281V at 600ms, and the current drops from

10A to 1.9A. This implies that the active power is shed from 1550W to 267W. This result shows that the resistive ES performs well in shedding power when the mains voltage drops.

C. Test c): Operation of the Proposed Power Flow Controller in a Subnetwork with an Intermittent Wind Power Injection



Fig. 15. Photograph of the AC/AC Buck converter.

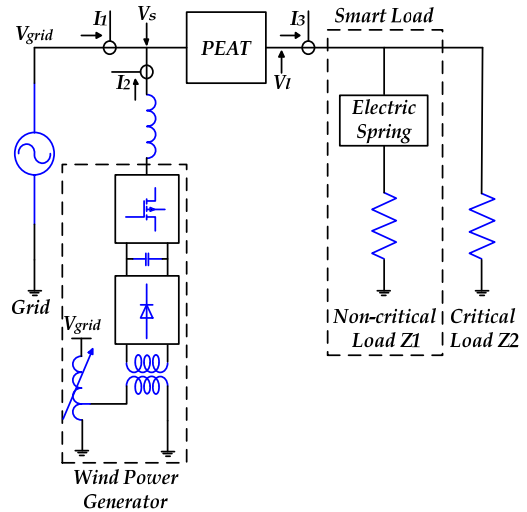


Fig. 17. Experiment setup schematic.

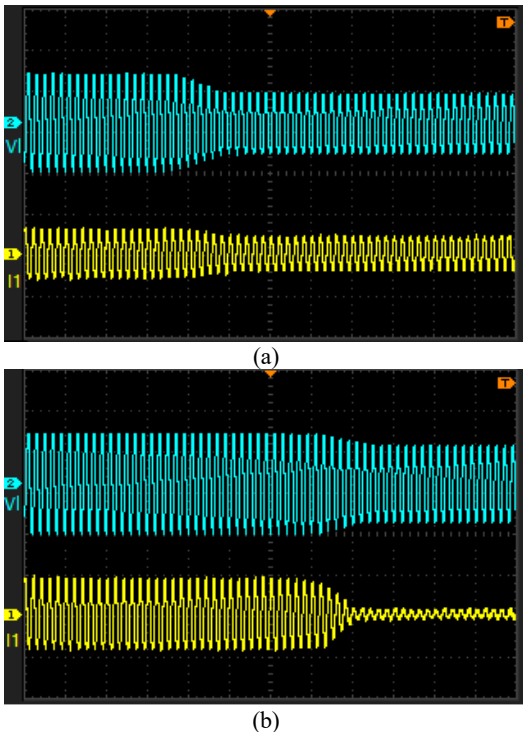


Fig. 16. Voltage and current curves of a smart load: (a) the ES gain is 0.05, CH1- I_l 15A/Div., CH2- V_l 150V/Div., Time Base

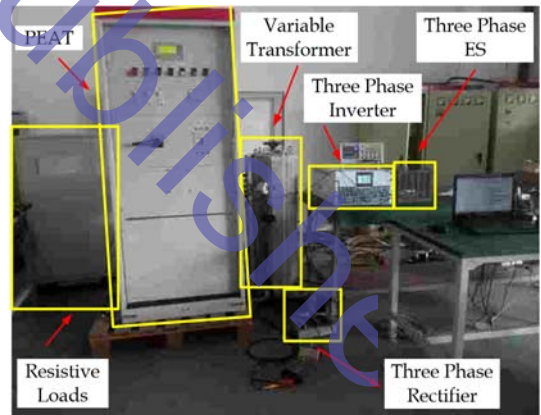


Fig. 18. Photograph of the practical experiment setup.

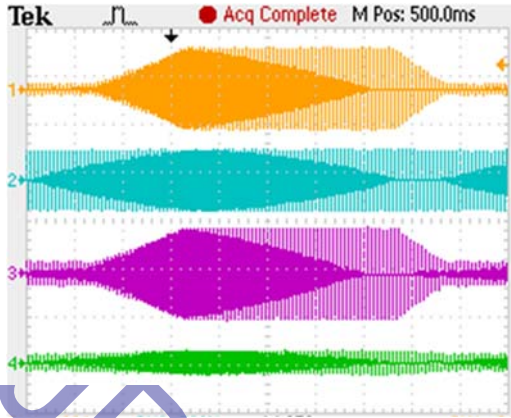


Fig. 19. Measured waveforms where CH1 - wind power generator current I_2 50A/Div., CH2 - Line voltage V_l 500V/Div., CH3 - Line current I_3 50A/Div., CH4 - Grid current I_1 50A/Div., Time Base 250ms/Div.

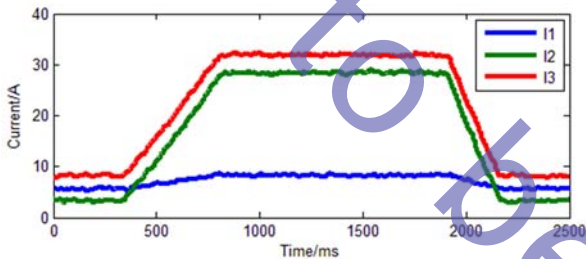


Fig. 20. RMS values of the currents with the grid current I_1 , wind power generator current I_2 and line current I_3 .

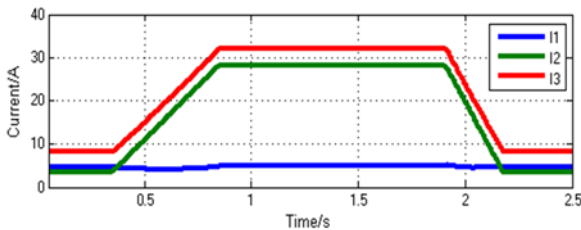


Fig. 21. Simulated RMS values of the currents with the grid current I_1 , wind power generator current I_2 and line current I_3 .

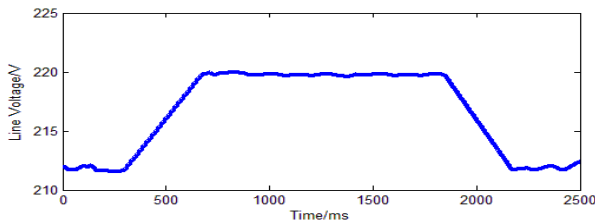


Fig. 22. RMS values of the line voltage.

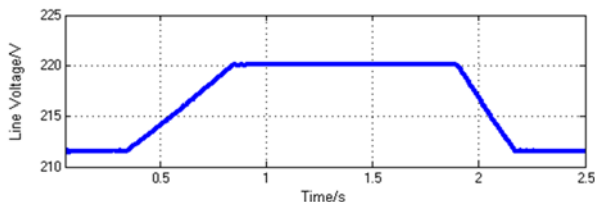


Fig. 23. Simulated RMS values of the line voltage.

A subnetwork system is built and the experimental setup schematic is shown in Fig. 17. The system includes a wind power generator, a PEAT, a smart load and a critical load.

The wind power generator applies a variable transformer to simulate intermittent wind power. The variable transformer varies the voltage by moving the tap changer, and then voltage is applied to the isolation transformer to isolate the voltage from the grid for protection purposes. The isolation transformer output voltage is regulated through a grid connected inverter to simulate intermittent wind power. The PEAT controller regulates the total load power to be balanced with wind power, which is the second power controller in Section V. The smart load automatically sheds the load power. Both the smart load and critical load are connected to the subnetwork. Waveforms of the power source voltage V_s , line voltage V_l , grid current I_1 , wind power generator current I_2 and line current I_3 are measured. Fig. 16 shows a photograph of the practical experiment setup. The test conditions are the grid phase voltage $V_{grid} = 220\text{Vac}$, non-critical load $Z_1 = 8.2\ \text{ohm}$, critical load $Z_2 = 43\text{ohm}$, G (the gain of the ES) = 31, P (the proportional gain of the power flow controller) = 8 and I (the integral gain of the power flow controller) = 2.

The power flow controller is activated and works throughout the experiment. The purpose of the experiment is to check the performance of power flow controller when wind energy changes. In the beginning, the wind power generator current I_2 is around 3.5A as shown in Fig. 20. It then begins to increase to 28.2A to inject more power into the system, which is simulated in this experiment by changing the tap-changer of the variable transformer of the wind power generator in Fig. 17. The wind power generator current I_2 then decreases to 3.5A again. The experiment result in Fig. 20 show that the line current I_3 increases from 8.2A to 32.0A when the wind power generator injects more power, and decreases to 8.2A when the wind power generator decreases the injected power. This implies that the total load power follows the wind power and that the power flow controller performs well. The grid current only changes slightly when the wind power changes, which shows that the total load power is balanced with the wind power and that the impact of the intermittent nature of the wind power generator on the grid is significantly reduced. Fig. 22 shows that the line voltage is increased by the PEAT and ES of the power flow controller when the wind power increases. As a result, more power is consumed by the load. Fig. 19 shows measured waveforms of the wind power generator current I_2 , line voltage V_l , line current I_3 and grid current I_1 . It shows that the line current follows the trend of the wind generator current and that the grid current only changes slightly when the wind generator current changes.

Fig. 21 shows MATLAB simulation results of the RMS values of the grid current I_1 , wind power generator current I_2 , line current I_3 and line voltage. Comparisons between Fig. 20

and Fig. 21 and between Fig. 22 and Fig. 23 show that the practical experiment results follow the simulation experiment results.

The obtained experiment results validate the function of the proposed power flow controller, which applies the second power controller in Section V. The total load power is balanced with the wind power and the impact of changes in the wind power have a slight impact on grid.

VIII. CONCLUSIONS

A novel power flow controller comprising a resistive ES and a PEAT has been developed. The principle behind the control strategy has been described in detail, and a stability analysis performed on the derived mathematical model for the controller shows that it is stable. Simulations carried out for different test cases on this model indicate the effectiveness of the proposed controller in shaping the power flow. An experimental setup is made, and it is shown that the obtained experimental results closely follow the simulation results, indicating that the model

of the power flow controller is valid. In addition, the stability analysis and effectiveness of the proposed power flow controller can be extended to actual realization.

The obtained results show that the PEAT plays the role of a global controller and the ES plays the role of a local controller. The combination of these two controllers makes the power flow control complete in terms of controlling the RES power to supply non-critical loads and grid power to supply critical loads. This way, the critical loads, which require a stable and reliable power supply, are guaranteed to be provided with power through the grid, and the non-critical loads can be supplied power through an intermittent but cheaper RES when it is available. If the RES produces abundant power, the critical loads can be supplied power through it instead of the grid.

It can be concluded that the proposed power flow controller is a promising and realizable way to mitigate the effect of the intermittent availability of the RES in the future grid and to ease the tension of the grid power supply to meet sudden changes in electricity demand.

APPENDIX

TABLE I
SYSTEM STABILITY ANALYSIS TEST DATA

k_{es}	V_l (V)	I_l (A)	I_2 (A)	V_{es} (V)	V_l (V)	λ_l	λ_2
0.5	206.0549	199.0824	206.0549	6.9725	199.0824	-1514.8+177.8i	-1514.8-177.8i
1	206.1834	192.3667	206.1834	13.8166	192.3667	-1.1675e3	-1.18626e3
2	206.4274	179.2823	206.4274	27.1452	179.2823	-0.8476e3	-2.3597e3
5	207.0713	142.4275	207.0713	64.6437	142.4275	-0.4773e3	-3.8784e3
10	207.9175	87.0926	207.9175	120.8249	87.0926	-0.2762e3	-7.0481e3
20	209.0533	-9.8798	209.0533	218.9332	-9.8798	-0.0148e3	-1.7656e3
30	209.7082	-99.0452	209.7082	308.7534	-99.0452	-0.0100e3	-4.4733e3

TABLE II
CASE STUDIES RESULTS

		Part1(1~5min)	Part2(6~9min)	Part3(10~13min)
Case 1)	Average Power Upstream(kW)	30.1	0.2	0.2
	Critical load power(kW)	6.5	6.8	11.4
	Non-critical load power(kW)	48.2	19.1	16.0
	Wind power(kW)	25.1	25.1	25.1
	Critical load voltage(V)	207.5	213.8	213.3
Case 2)	Average Power Upstream(kW)	30.1	7.1	11.7
	Critical load power(kW)	6.5	6.9	11.6
	Non-critical load power(kW)	48.2	25.3	25.1
	Wind power(kW)	25.1	25.1	25.1
	Critical load voltage(V)	207.5	214.5	214.6
Case 3)	Average Power Upstream(kW)	30.1	0.2	0.3
	Critical load power(kW)	6.5	6.9	11.4
	Non-critical load power(kW)	48.2	17.9	16.5
	Wind power(kW)	25.1	25.1	25.1
	Critical load voltage(V)	207.5	213.9	213.3

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